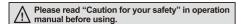
Multi-channel (4 channel / 2 channel) modular type PID control

Features

- Multi-channel(4 channel/ 2 channel) simultaneous controlling possible
- High-speed sampling cycle(4 channel: 100ms, 2 channel: 50ms)
- No communication and power supply for expansion modules required by using side connectors: Max. 31 units (124 channels / 62 channels)
- Input channel isolated design(Dielectric strength 1,000 VAC)
- Heating/Cooling simultaneous controlling
- Allows parameter setting by USB port of PC
 - : Free download the integrated device management program(DAQMaster)

 - : SCM-WF48(Wi-Fi to RS485/USB communication converter(availabe soon), SCM-US(USB to Serial converter), SCM-38I(RS-232C to RS485 converter), SCM-US48I(USB to RS485 converter)
- Parameter setting by SCM-US without power/wiring
- Easy maintenance via connector type connection
 - : Sensor input connector, control output connector, power/communication connector
- Multi input / Multi range
- Heater disconnection function(CT input)
 \(\times CT, \text{ sold separately: CSTC-E80LN, CSTC-E200LN} \)





Manual

- Visit our website (www.autonics.com) to download user manual and communication manual.
- User manual describes for specifications and function, and communication manual describes for RS485 communication (Modbus RTU protocol) and parameter address map data.

Integrated device management program(DAQMaster)

- DAQMaster is a integrated device management program for convenient management of parameters and multiple device data monitoring.
- Visit our website (www.autonics.com) to download user manual and integrated device management program.
- < Computer specification for using software >

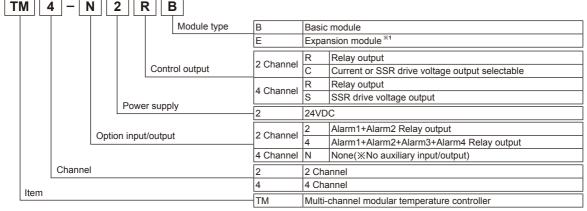
Item	Minimum requirements
System	IBM PC compatible computer with Intel Pentium III or above
Operating system	Microsoft Windows 98/NT/XP/Vista/7
Memory	256MB or more
Hard disk	More than 1GB of free hard disk space
VGA	1024×768 or higher resolution display
Others	RS-232 serial port(9-pin), USB port

< DAQMaster screen >



Line-up

Ordering information



*Make sure to purchase both expansion module and basic module together because power supply/communication terminals are provided with basic modules only.

H-10 Autonics

Specifications

Series		TM2- 22RB	TM2- 42RB	TM2- 22RE	TM2- 42RE	TM2- 22CB	TM2- 42CB	TM2- 22CE	TM2- 42CE	TM4- N2RB	TM4- N2RE	TM4- N2SB	TM4- N2SE
Channel		2 Chann	1							4 Chan (Each c		sulated-	
Power Sup	ply	24VDC									<u> </u>	,,-	
Allowable v	oltage range	90 to 110	0% of rate	d voltage)							,	
Power cons	sumption	Max. 5W	1										
Display typ	e	Non-disp	olay type F	Paramete	er setting	& monito	ring with e	external d	evices (Po	C or PLC)		
Input	RTD	DPt1000	Ω, JPt100	Ω 3 wire ((allowabl	e line resi	stance m	ax. 5Ω pe	r a wire)				
type	Thermocouple	K, J, E, 1	Γ, L, N, U,	R, S, B,	C, G, PL	II (13type	s)						
Display	RTD Thermocouple*1	(PV ±0.5	i% or ±1℃	C, select t	the highe	er one) ±1	digit Max.						
accuracy	CT input	±5% F.S	. ±1digit N	Лах.						<u> </u>			
	Current output	±1.5% F.	S. ±1digit	Max.						1—			
Influence of	RTD	(PV ±0.5	% or ±2°C	, select t	he higher	one) ±1d	igit Max.(n case of	thermoco	uple inpu	t, it is ±5°C	at -100°	°C below.
temperature *2	Thermocouple	• Thermo	ocouples l	_, U, C, G	6, R, Š, B	3: (PV ±0.	5% or ±5°	C, select	the highe	r one) ±10	digit Max.		
Relay 250VAC 3A 1a — 250VAC 3A 1a -									<u> </u>				
Control output	SSR	_					±3V 30m			_		22VDC Max.	±3V30m
	Current	DC 4-20mA or DC 0-20m selectable(load 500Ω Ma											
Option	Relay	250VAC 3A 1a —											
output	Communication	RS485 C	RS485 Communication output (Modbus RTU)										
	CT input	0.0-50.0A(Primary current meaurement range)											
Option input	Digital input	Non-co	Contact input: ON Max. 1kΩ, OFF Min. 100kΩ Non-contact input: ON Max. 1.5V residual voltage, OFF Max. 0.1mA leakage current Outflow current: Approx. 0.5mA										
Control method	Heating, cooling Heating&cooling	ON/OFF	control m	ode, P, F	PI, PD, PI	ID control	mode						
Hysteresis		1 to 100°	1 to 100°C/°F (0.1 to 100°C/°F) variable							1 to 100 digit			
Proportiona	al band (P)	0.1 to 99	9.9°C/°F										
Integral tim	e (I)	0 to 9999 sec.											
Derivative t	ime (D)	0 to 9999 sec.											
Control per	iod (T)	0.1 to 12	0.0 sec. (only rela	y output a	and SSR	drive volta	age outpu	t type)				
Manual res	et value	0.0 to 10	0.0%										
Sampling p	eriod	50ms 100ms (2 channel synchronous sampling) (4 channel synchrono								ronoue co	mnlina\		
Dielectric s	trenath	(2 channel synchronous sampling) (4 channel synchronous samplin 1,000VAC 50/60Hz for 1 min. (between power source terminal and input terminal)									mpiliy)		
Vibration		· ·					_		of X, Y, Z		s for 2 ho	urs	
Relay	Mechanical		000,000					,	, ., =				
life cycle	Electrical		,000 oper	-		A resistar	nce load)						
Insulation r			at 500VD				,						
Noise resis					<u> </u>	e width: 1	us) by the	e noise si	mulator				
Environ-	Ambient -10 to 50°C storage: -20 to 60°C								,				
ment	Ambient humidity	35 to 85°	%RH, sto	rage: 35 t	to 85%R	Н							
Accessory		<u> </u>	on connec		nnector (⊛Basic π	nodule on	ly)					
Insulation t	уре	Double ii		or reinfor				• /	rength be	tween the	measurir	ng input p	art
Approval		(F:3)	us										
		A	Approx.	Approx.	Approx	Approx	Approx	Approx.	Approx.	Approx	Approx.	Approx.	Approx

^{%1:} In case of thermocouple K, T, N, J, E at -100°C below and L, U, PlatinelII, it is ±2°C ±1digit Max.

isplay nit P) Switching node power supply H-11

Autonics

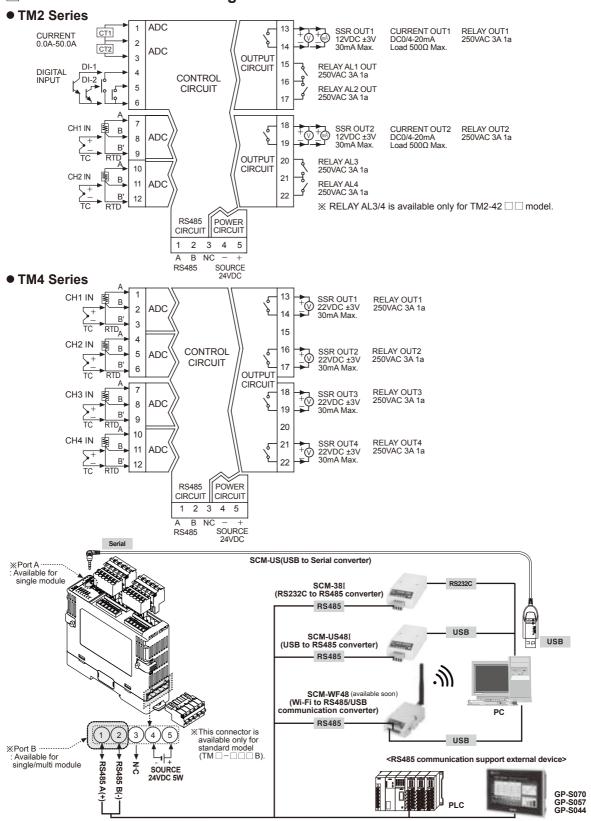
In case of thermocouple B, display accuracy cannot be ensured under 400°C.

In case of thermocouple R, S at 200°C below and thermocouple C, G, it is 3°C ±1digit Max.

^{※2:} Applied when used out of range 23 ±5°C.

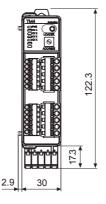
^{*}Environment resistance is rated at no freezing or condensation

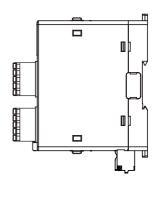
Connections and block diagram



H-12 Autonics

Dimensions





(A) Photo electric sensor

(unit: mm)

(B) Fiber optic sensor

> (C) Door/Area

(D) Proximity

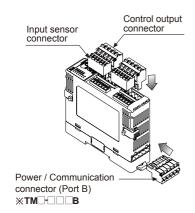
(E) Pressure

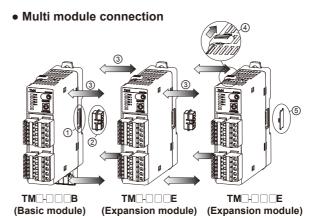
(F) Rotary

(G) Connector/

Installation

• Connector connection

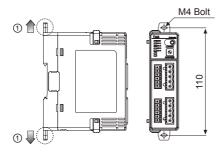




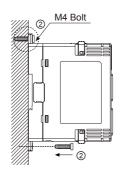
- ※① Remove END cover for both basic modules and expansion modules.
 - ② Insert expansion connectors.
 - ③ Connect an expansion module without space.
 - 4 Fix the LOCK switch by pushing it in the LOCK direction.
 - ⑤ Mount the END cover at each side.

※Up to 30 expansion modules can be connected to a basic module. Use an adequate power supply system for the power input specifications and overall capacity. [Maximum power (155W=31ea X 5W) is required when connecting 31 units]

Bolt Inserting



① Pull each Rail Lock switch up and down.



② Insert the bolts to fix. (Tightening torque is 0.5N·m to 0.9N·m.) (H) Temp. controller

(I) SSR/ Power controller

(J) Counter

imer

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor

(P) Switching mode power supply

(Q) Stepper motor&

(R) Graphic/ Logic panel

(S) Field

(T) Software

(U)

Autonics H-13

TM Series

DIN Rail Installation

[Installation method]

- ① Put the top edge of the rail Lock on the top edge or the DIN rail.
- 2 Push the module body in while pressing down.





[Removal method] 1 Press down the module body.

2 Pull the module body forward.



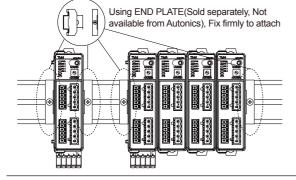
Make sure to install the unit vertically to the ground.





Vertical Installation (O)

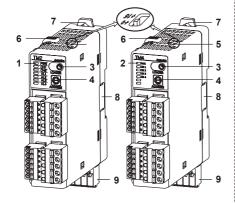
Horizontal Installation (X)



Parts description

TM2 Series

TM4 Series



3. PC loader port(Port A)

Integrated device management program (DAQMaster, free download on our site) is for setting parameter by PC through USB to Serial converter (SCM-US, sold separately).

4. Communication address setting switch(SW1)

Used to set communication address.

5. Communication address group change switch(SW2)

When communication address is over 16, select +16. Ex)For setting 20 address, set the communication address group change switch (SW) as +16 and set the commuicaiton address setting switch (SW1) as 4.

6. Lock switch

Used for fixing units to DIN rail or to the wall

7. Rail Lock

Used for fixing each module when connecting module units. (up/down side)

- 8. END Cover: Remove it when connecting each module.
- 9. Power supply / communications connector(PortB)

Only Basic module TM□-□2□B

1. Display LED(TM2 Series)

Status			Alarm output				
	Initial power on*1	Control output	N.O. Alarm oc	curred	N.C. Alarm occ	Auto tuning ^{*2}	
Display LED			OFF(OPEN)	ON(CLOSE)	OFF(CLOSE)	ON(OPEN)	
PWR LED ^{*3}	Green	Green					Green
CH1 LED	2400bps-Flashing	ON-RED	_				Flashing
CH2 LED	4800bps-Flashing	ON-RED	_				Flashing
AL1 LED	9600bps-Flashing	ON-Yellow ^{*4}	Light OFF	Light ON	Light OFF	Light ON	Light OFF
AL2 LED	19200bps-Flashing	ON-Yellow ^{×5}	Light OFF	Light ON	Light OFF	Light ON	Light OFF
AL3 LED	38400bps-Flashing	_	Light OFF	Light ON	Light OFF	Light ON	Light OFF
AL4 LED	_	_	Light OFF	Light ON	Light OFF	Light ON	Light OFF

2. Display LED(TM4 Series)

Display LED	Initial power on ^{*1}	Control output	Auto tuning**2
PWR LED**3	Green	Green	Green
CH1 LED	2400bps-Flashing	ON-RED	Flashing
CH2 LED	4800bps-Flashing	ON-RED	Flashing
CH3 LED	9600bps-Flashing	ON-RED	Flashing
CH4 LED	19200bps-Flashing	ON-RED	Flashing
	38400bps-Flashing	_	

- X1: In case of initial power on, default communication speed will be flashing for 5 sec. (1 sec. cycle).
- X2: Each CH3 LED will be flashing during auto tuning (1 sec. cycle).
- X3: Power LED will be flashing while communicating with external units (1 sec. cycle).
- X4: Light ON when control type for CH1 is heating & cooling type and cooling output is provided.
- %5. Light ON when control type for CH2 is heating & cooling type and cooling output is provided.

■ Input sensor type and temperature range

Input sensor		No.	Dot	Display	Input range (°C)	Input range (°F)
	K(CA)	0	1	K(CA).H	-200 to 1350	-328 to 2462
	K(CA)	1	0.1	K(CA).L	-200.0 to 1350.0	-328.0 to 2462.0
	1/10)	2	1	J(IC).H	-200 to 800	-328 to 1472
	J(IC)	3	0.1	J(IC).L	-200.0 to 800.0	-328.0 to 1472.0
	E(CD)	4	1	1 E(CR).H -200 to 8		-328.0 to 1472
	E(CR)	5	0.1	E(CR).L	-200.0 to 800.0	-328.0 to 1472.0
	T(CC)	6	1	T(CC).H	-200 to 400	-328 to 752
	T(CC)	7	0.1	T(CC).L	-200.0 to 400.0	-328.0 to 752.0
	B(PR)	8	1	B(PR)	0 to 1800	32 to 3272
Thermocouple	R(PR)	9	1	R(PR)	0 to 1750	32 to 3182
	S(PR)	10	1	S(PR)	0 to 1750	32 to 3182
	N(NN)	11	1	N(NN)	-200 to 1300	-328 to 2372
	C(TT) ^{×1}	12	1	C(TT)	0 to 2300	32 to 4172
	G(TT) ^{×2}	13	1	G(TT)	0 to 2300	32 to 4172
	1 (10)	14	1	L(IC).H	-200 to 900	-328 to 1652
	L(IC)	15	0.1	L(IC).L	-200.0 to 900.0	-328.0 to 1652.0
	11(00)	16	1	U(CC).H	-200 to 400	-328 to 752
	U(CC)	17	0.1	U(CC).L	-200.0 to 400.0	-328.0 to 752.0
	Platinel II	18	1	PLII	0 to 1400	32 to 2552
	JPt 100Ω	19	1	JPt100.H	-200 to 600	-328 to 1112
DTD	JP1 100Ω	20	0.1	JPt100.L	-200.0 to 600.0	-328.0 to 1112.0
KIU	DPt 100Ω	21	1	DPt100.H	-200 to 600	-328 to 1112
Thermocouple	ρει 100Ω	22	0.1	DPt100.L	-200.0 to 600.0	-328.0 to 1112.0

X1: C(TT): Same as existing W5(TT).
XDefault: K(CA).H

※2: G(TT): Same as existing W(TT).

■ Error indication

	Input sensor open error	Over temperature range
PWR LED	Red ON	
CH1 LED	RED Flashing (for 0.5 sec.)	
CH2 LED	RED Flashing (for 0.5 sec.)	
CH3 LED ^{*1}	RED Flashing (for 0.5 sec.)	
CH4 LED *1	RED Flashing (for 0.5 sec.)	
Communication output (decimal)	'31000' output	'30000 (upper limit)' output, '-30000 (lower limit)' output
Dedicated program	'OPEN' indication	'HHHH (upper limit)' indication , 'LLLL (lower limit)' indication

X1: Only for TM4 Series(4CH).

Communication setting

A function for external parameter setting & monitoring with PC or PLC.

Interface

Application Standard	Compliance with EIA RS 485
Max. connection	31 units (communication address setting: 01 to 31)
Communication type	Two wire, Half Duplex
Synchronization method	Asynchronous
Communication distance	Max. 800m
Communication speed(bps)	2400, 4800, 9600(default),19200, 38400
Communication response time	5 to 99ms
Start Bit	1bit(fixed)
Stop Bit	1bit, 2bit(default)
Parity Bit	None(default), Odd, Even
Data Bit	8bit(fixed)
Protocol	Modbus RTU

※Overlapped address setting is not allowed on the same communication line. Twisted Pair wires(for RS485 communication) must be used for communication cable.

• Communication speed indication

Current communication speed will be flashing in case of initial power ON for 5 sec. (1 sec. cycle).



*One module communication is allowed for Port A. Communication speed is fixed to 9600bps.

※Simultaneous monitoring can not be done for Port A and B since Port A is for parameter setting only.

※If connects communication through Port A, Port B will be disconnected communication automatically.

(A) Photo electric sensor

(C) Door/Area sensor

(D) Proximity sensor

Pressure sensor

encoder

Connector/ Socket

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

(M) Tacho/

(N)

(O) Sensor controller

(P) Switching mode power supply

(Q) Stepper motor& Driver&Controlle

Driver&Controlle

(R)
Graphic/
Logic
panel

(S) Field network device

(T) Software

(U) Other

Autonics H-15

TM Series

. Communication address setting

Set the communication address using SW1 and SW2.

Setting range is 01 to 31. (XIn case setting 00, communication is not available.)

SW1	Q S D G S	1											※Def	ault- SV	V1: 1, S	SW2: +0
SW2	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
+0 +16	∞ <	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
+0 +16	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31

Sold separately

O Communication converter



- SCM-38I (RS232C to RS485 converter)
 - **C**€ [3
- SCM-US48I (USB to RS485 converter)
- **C**€ [6]
- SCM-US (USB to Serial converter)

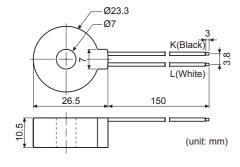


 Max. load current: 80A(50/60Hz) **XMax.** load current for TM Series

is 50A.

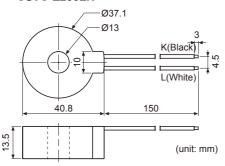
Ourrent transformer(CT)

• CSTC-E80LN



F=50Hz OUTPUT IN VOLTS RMS(V) • Current ratio: 1/1000 • Wire wounded resistance: 31Ω±10% 0.01 0.001 SENSED CURRENT IN AMPS RMS(Io)

• CSTC-E200LN



- 10 OUTPUT IN VOLTS RMS(V) • Max. load current: 200A(50/60Hz) XMax. load current for TM Series is 50A. • Current ratio: 1/1000 • Wire wounded resistance: 20Ω±10% 0.01 0.001 0.1 SENSED CURRENT IN AMPS RMS(Io)
- XDo not supply primary current in case that CT output is open. High voltage will be generated in CT output. **The current for above two CTs is 50A same but inner hole sizes are different. Please use this your environment.

H-16 **Autonics**

Proper usage

O Simple failure diagnosis

- When display LED is flashing every 0.5 sec. or when error message is indicated on external units
 - It represents input sensor open error. Cut off the power of controller and check input sensor connection.

If sensor is properly connected, disconnect sensor line from the controller and short the input terminal (+) / (-). Then, make sure that current indoor temperature is indicated. If current indoor temperature is properly indicated, it represents no errors detected. If external unit displays 'HHHH' or 'LLLL', please contact our A/S center.

(Current indoor temperature checking is available only if selecting thermocouple type.)

· Make sure proper input sensors are selected.

. When no output is operated

 Check output display LED at the front. In case output display LED does not work properly, please check each parameter setting again. In case output display LED works properly, disconnect the output terminal and check controller's output type (Relay contact, SSR, Current) again.

When external units receive no response or error data

- · Check communication converter first.
- Do not install the unit with overlapping communication converter lines and AC power supply lines.
- Use separate power supply (24VDC) for communication converter if possible.
- Strong external noise could be a possible cause for this symptom. Please contact our A/S center. In addition, analyze the main cause that triggers strong noise and take measures to prevent it. Even though this unit complies with proper noise resistance standards, consistent noise induction could affect internal circuit break.

When communication does not work properly

- · Check converter's power supply and connection.
- · Check communication setting.
- Check main body's connections to external units.

O Caution for using

- Use DC power only.
- Keep the ambient temperature -10°C to 50°C.
- For more accurate controlling, start temperature controlling approx. 20 minutes later after connecting input sensors and supplying power.
- In case display accuracy does not meet the specification, check Input Bias parameter first.
- Power switch or a circuit breaker must be installed for proper application.
- Make sure that the power switch or a circuit breaker installed near operators.
- This unit is solely allowed for temperature controlling application. Do not apply this unit as a voltage meter or current meter.
- When line extension is required, please use specified compensation line. If not, there occurs temperature difference at the joint part between thermocouples and extension lines.
- In case of using RTD, line connection must be done with 3 wires. When line extension is required, use the same wire with material, thickness and length. Different line resistance may cause temperature difference.
- Make sure controller's line connection must be separated from high voltage line or power supply line in order to prevent induced noise.
- If it is required that power supply line should be connected near input signal line, use line filter on controller's power supply line and input signal line must be shielded.
- Avoid installing controllers adjacent to high frequency noise generating units including high frequency soldering machine, high frequency sewing machine, and high capacity SCR controllers and motors.
- Avoid using the unit near radio, TV or wireless machines that may cause high frequency interference.
- When changing input sensors, power off the controller first. Connect input sensors as specified and supply the power again. Then, change & download related parameters using PC loader program.
- Use (-) driver screws (2mm) or use plastic driver screws. If not, it might cause product damage.
- Twist Pair wires must be used for communication cable.
 Connect Ferrite Bead at each end of line in order to reduce the effect of external noise.
- Avoid installing the unit with overlapping communication line and AC power line together.
- Draw a draft while using the controllers. In case of installing at a closed area, please take measures for ventilation.
- Installation environment
 - It shall be used indoor.
- · Altitude Max. 2000m.
- Pollution Degree 2
- · Installation Category II.

(A) Photo electric sensor

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity sensor (E) Pressure

(F) Rotary

(G) Connector/

(H) Temp. controller

(I) SSR/ Power controller

(J) Counter

imer

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

0)

(P) Switching mode power supply

(Q) Stepper motor&

(R) Graphic/ Logic panel

(S) Field network

> T) Software

U) Other

Autonics H-17